



R.C.L SERIES CURRENT II

Thirteen lecture

Electrical engineering

Student name:

Department:

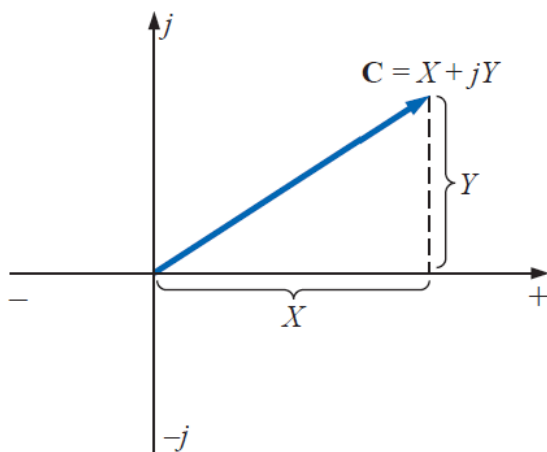
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13.1 Complex Numbers

A complex number represents a point in a two-dimensional plane located with reference to two distinct axes

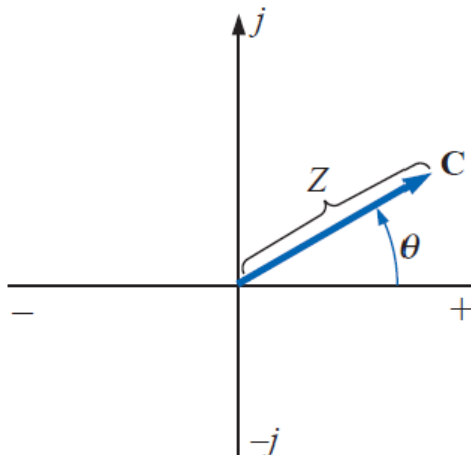
- The horizontal axis is called the real axis, while the vertical axis is called the imaginary axis.
- Two forms are used to represent a complex number: rectangular and polar.

1) **Rectangular Form:** The format for the rectangular form is



$$C = X + jY$$

2) **Polar Form:** The format for the **polar form** is:



$$C = Z \angle \theta$$

$$-C = -Z \angle \theta = Z \angle \theta \pm 180^\circ$$

Mathematical Operations with Complex Numbers:

Complex numbers lend themselves readily to the basic mathematical operations of addition, subtraction, multiplication, and division.

$$j = \sqrt{-1}$$

$$j^2 = -1$$

$$\frac{1}{j} = -j$$

1) Addition

$$\mathbf{C}_1 = \pm X_1 \pm j Y_1 \quad \text{and} \quad \mathbf{C}_2 = \pm X_2 \pm j Y_2$$

$$\mathbf{C}_1 + \mathbf{C}_2 = (\pm X_1 \pm X_2) + j (\pm Y_1 \pm Y_2)$$

EXAMPLE:

- Add $\mathbf{C}_1 = 2 + j4$ and $\mathbf{C}_2 = 3 + j1$.
- Add $\mathbf{C}_1 = 3 + j6$ and $\mathbf{C}_2 = -6 + j3$.

Solutions:

a)

$$\mathbf{C}_1 + \mathbf{C}_2 = (2 + 3) + j(4 + 1) = \mathbf{5 + j5}$$

b)

$$\mathbf{C}_1 + \mathbf{C}_2 = (3 - 6) + j(6 + 3) = \mathbf{-3 + j9}$$

2) Multiplication

$$\mathbf{C}_1 = X_1 + j Y_1 \quad \text{and} \quad \mathbf{C}_2 = X_2 + j Y_2$$

$$\mathbf{C}_1 \cdot \mathbf{C}_2 = (X_1 X_2 - Y_1 Y_2) + j(Y_1 X_2 + X_1 Y_2)$$

$$\mathbf{C}_1 = Z_1 \angle \theta_1 \quad \text{and} \quad \mathbf{C}_2 = Z_2 \angle \theta_2$$

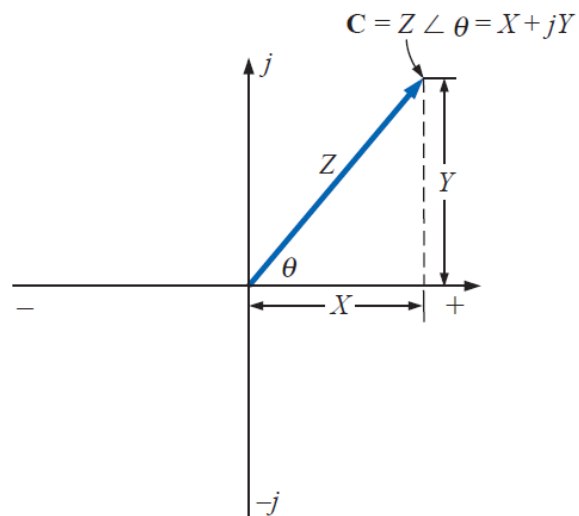
$$\mathbf{C}_1 \cdot \mathbf{C}_2 = Z_1 Z_2 \angle \theta_1 + \theta_2$$

3) Division

$$C_1 = Z_1 \angle \theta_1 \quad \text{and} \quad C_2 = Z_2 \angle \theta_2$$

$$\frac{C_1}{C_2} = \frac{Z_1}{Z_2} \angle \theta_1 - \theta_2$$

13.2 Conversion Between Forms



1) Rectangular to Polar

$$Z = \sqrt{X^2 + Y^2}$$

$$\theta = \tan^{-1} \frac{Y}{X}$$

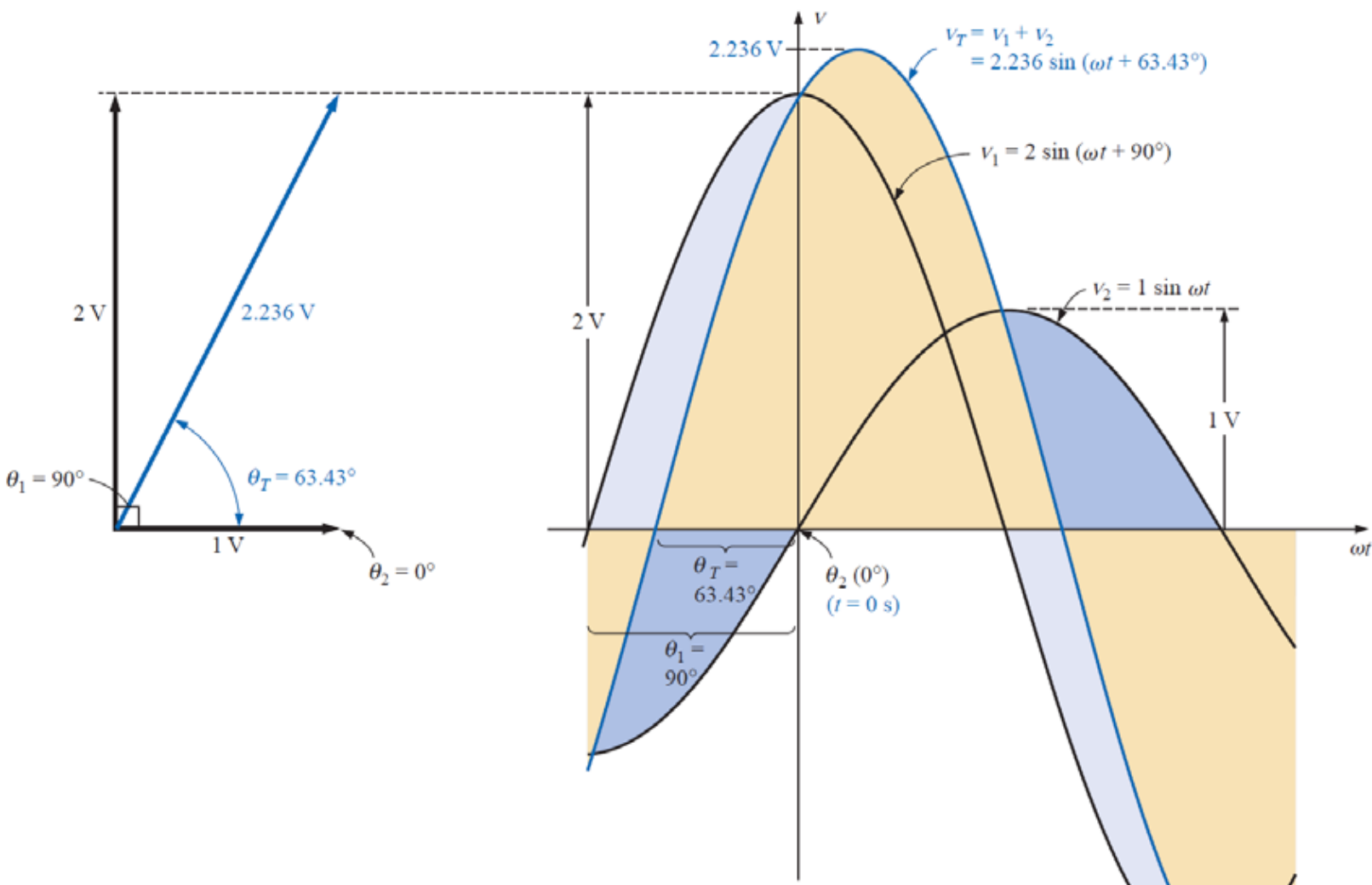
2) Polar to Rectangular

$$X = Z \cos \theta$$

$$Y = Z \sin \theta$$

13.3 Phasors:

The radius vector, having a constant magnitude (length) with one end fixed at the origin, is called a **phasor** (المتجه) when applied to electric circuits.



$$e = V_m \sin(\omega t + \theta) \Rightarrow e = \frac{V_m}{\sqrt{2}} \angle \theta = 0.707 V_m \angle \theta$$

EXAMPLE: Convert the following from the time to the phasor domain:

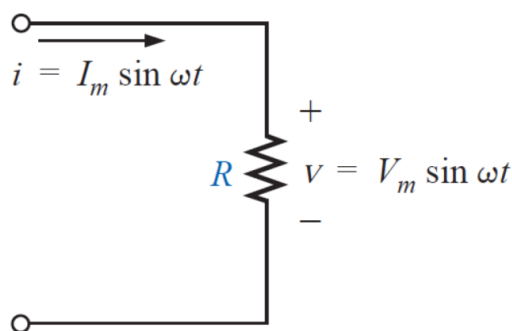
Time Domain	Phasor Domain
a. $\sqrt{2}(50) \sin \omega t$	$50 \angle 0^\circ$
b. $69.6 \sin(\omega t + 72^\circ)$	$(0.707)(69.6) \angle 72^\circ = \mathbf{49.21 \angle 72^\circ}$
c. $45 \cos \omega t$	$(0.707)(45) \angle 90^\circ = \mathbf{31.82 \angle 90^\circ}$

EXAMPLE: Write the sinusoidal expression for the following phasors if the frequency is 60 Hz:

Phasor Domain	Time Domain
a. $\mathbf{I} = 10 \angle 30^\circ$	$i = \sqrt{2}(10) \sin(2\pi 60t + 30^\circ)$ and $i = \mathbf{14.14 \sin(377t + 30^\circ)}$
b. $\mathbf{V} = 115 \angle -70^\circ$	$v = \sqrt{2}(115) \sin(377t - 70^\circ)$ and $v = \mathbf{162.6 \sin(377t - 70^\circ)}$

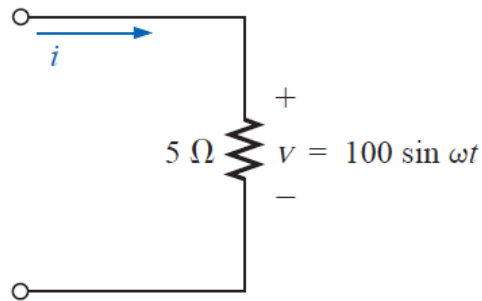
13.4 Impedance and The Phasor Diagram

1) Resistive Elements



$$\mathbf{Z}_R = R \angle 0^\circ$$

EXAMPLE: find the current I for the circuit. Sketch the waveforms of v and I .

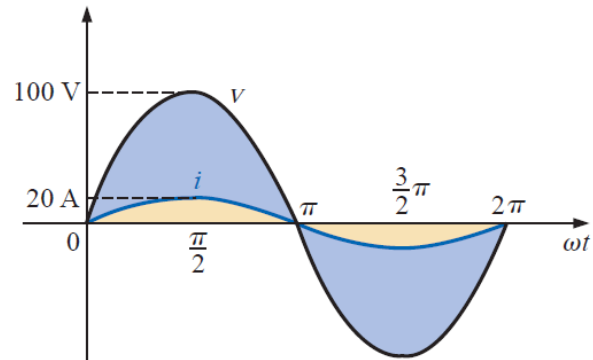
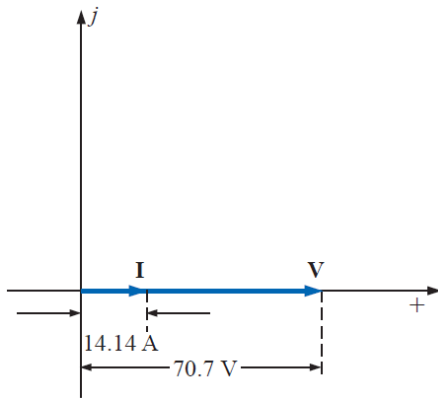


Solutions:

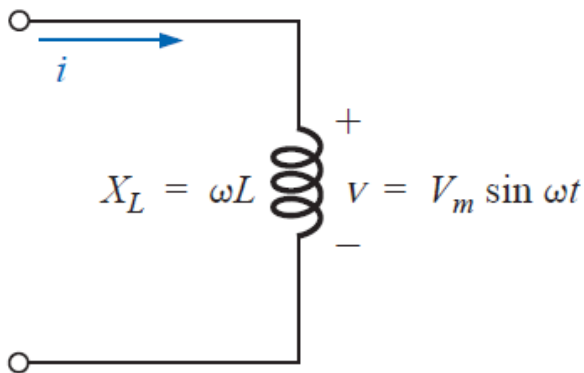
$$v = 100 \sin \omega t \Rightarrow \text{phasor form } \mathbf{V} = 70.71 \text{ V } \angle 0^\circ$$

$$\mathbf{I} = \frac{\mathbf{V}}{\mathbf{Z}_R} = \frac{V \angle \theta}{R \angle 0^\circ} = \frac{70.71 \text{ V } \angle 0^\circ}{5 \Omega \angle 0^\circ} = 14.14 \text{ A } \angle 0^\circ$$

$$i = \sqrt{2}(14.14) \sin \omega t = \mathbf{20 \sin \omega t}$$

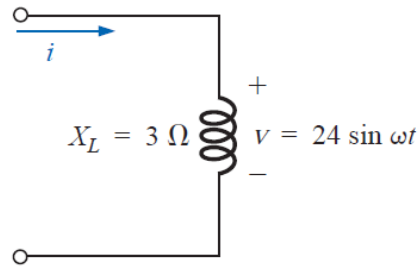


2) Inductive Reactance



$$\mathbf{Z}_L = X_L \angle 90^\circ$$

EXAMPLE: find the current I for the circuit. Sketch the v and I curve

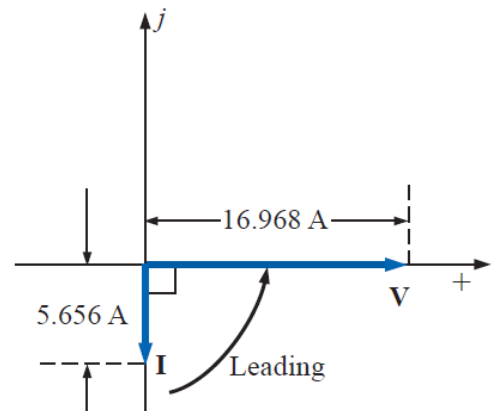
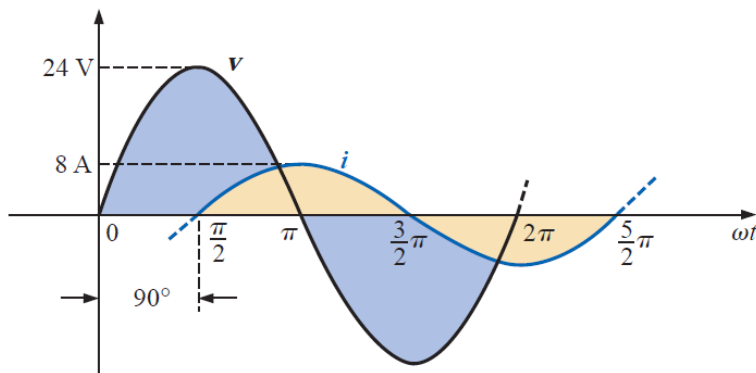


Solutions:

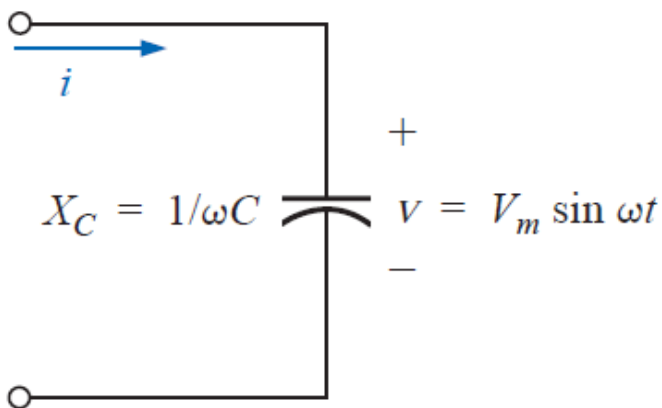
$$v = 24 \sin \omega t \Rightarrow \text{phasor form } \mathbf{V} = 16.968 \text{ V } \angle 0^\circ$$

$$\mathbf{I} = \frac{\mathbf{V}}{\mathbf{Z}_L} = \frac{V \angle \theta}{X_L \angle 90^\circ} = \frac{16.968 \text{ V } \angle 0^\circ}{3 \Omega \angle 90^\circ} = 5.656 \text{ A } \angle -90^\circ$$

$$i = \sqrt{2}(5.656) \sin(\omega t - 90^\circ) = 8.0 \sin(\omega t - 90^\circ)$$

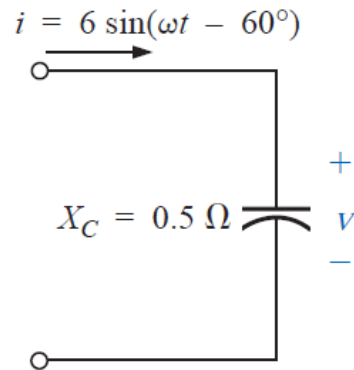


3) Capacitive Reactance



$$\mathbf{Z}_C = X_C \angle -90^\circ$$

EXAMPLE: find the voltage v for the circuit. Sketch the v and i curves.

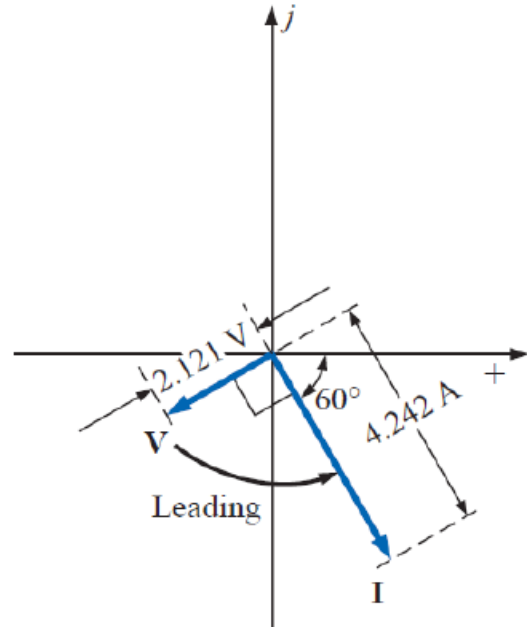
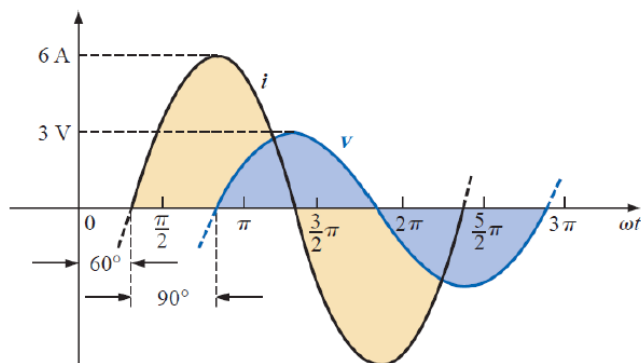


Solutions:

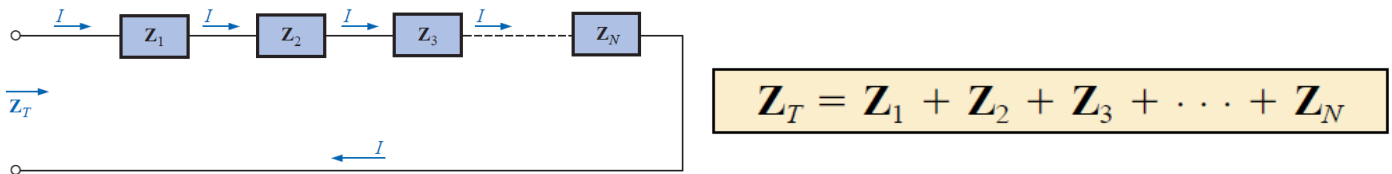
$$i = 6 \sin(\omega t - 60^\circ) \Rightarrow \text{phasor notation } \mathbf{I} = 4.242 \text{ A } \angle -60^\circ$$

$$\begin{aligned} \mathbf{V} &= \mathbf{I} \mathbf{Z}_C = (I \angle \theta)(X_C \angle -90^\circ) = (4.242 \text{ A } \angle -60^\circ)(0.5 \Omega \angle -90^\circ) \\ &= 2.121 \text{ V } \angle -150^\circ \end{aligned}$$

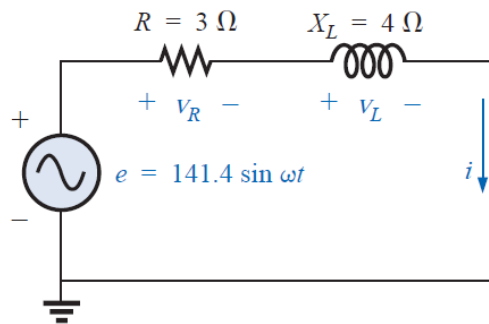
and $v = \sqrt{2}(2.121) \sin(\omega t - 150^\circ) = 3.0 \sin(\omega t - 150^\circ)$



13.5 Series Configuration



EXAMPLE: Determine the input impedance to the series network and find I , V_R , V_L . Draw the impedance diagram.



Solutions:

$$e = 141.4 \sin \omega t \Rightarrow E = 100 \text{ V } \angle 0^\circ$$

$$Z_T = Z_1 + Z_2 = 3 \Omega \angle 0^\circ + 4 \Omega \angle 90^\circ = 3 \Omega + j4 \Omega$$

$$Z_T = 5 \Omega \angle 53.13^\circ$$

$$I = \frac{E}{Z_T} = \frac{100 \text{ V } \angle 0^\circ}{5 \Omega \angle 53.13^\circ} = 20 \text{ A } \angle -53.13^\circ$$

$$V_R = IZ_R = (20 \text{ A } \angle -53.13^\circ)(3 \Omega \angle 0^\circ) = 60 \text{ V } \angle -53.13^\circ$$

$$V_L = IZ_L = (20 \text{ A } \angle -53.13^\circ)(4 \Omega \angle 90^\circ) = 80 \text{ V } \angle 36.87^\circ$$

